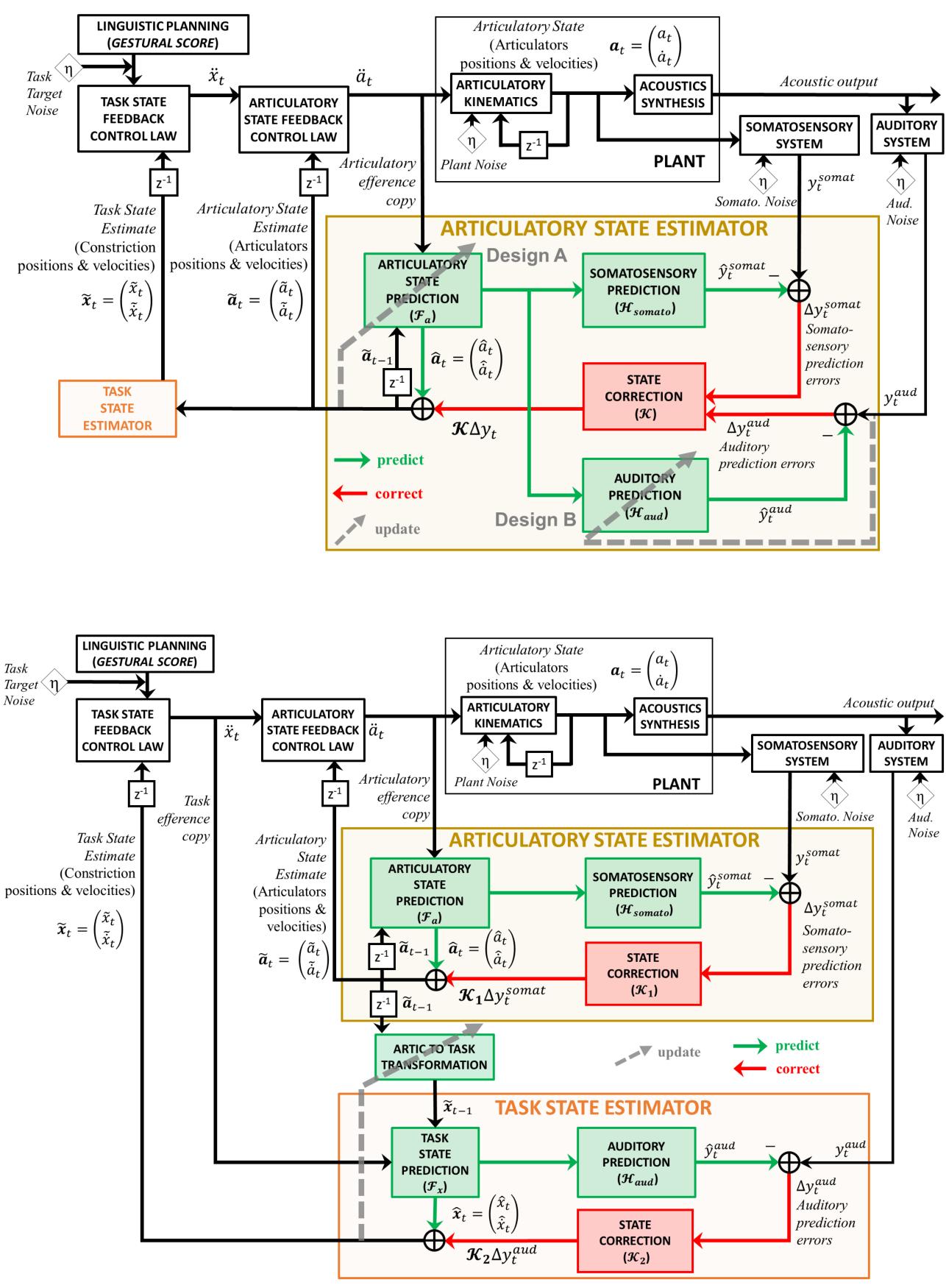
Sensorimotor adaptation in a hierarchical state feedback control model of speech



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Introduction and Method

- Auditory prediction error-based mechanisms involved in speech auditorymotor adaptation were examined via the feedback aware control of tasks in speech (FACTS) model.
- Consistent with theoretical perspectives in both non-speech and speech motor control, the hierarchical architecture of FACTS relies on both the higher-level task (vocal tract constrictions) as well as lower-level articulatory state representations.



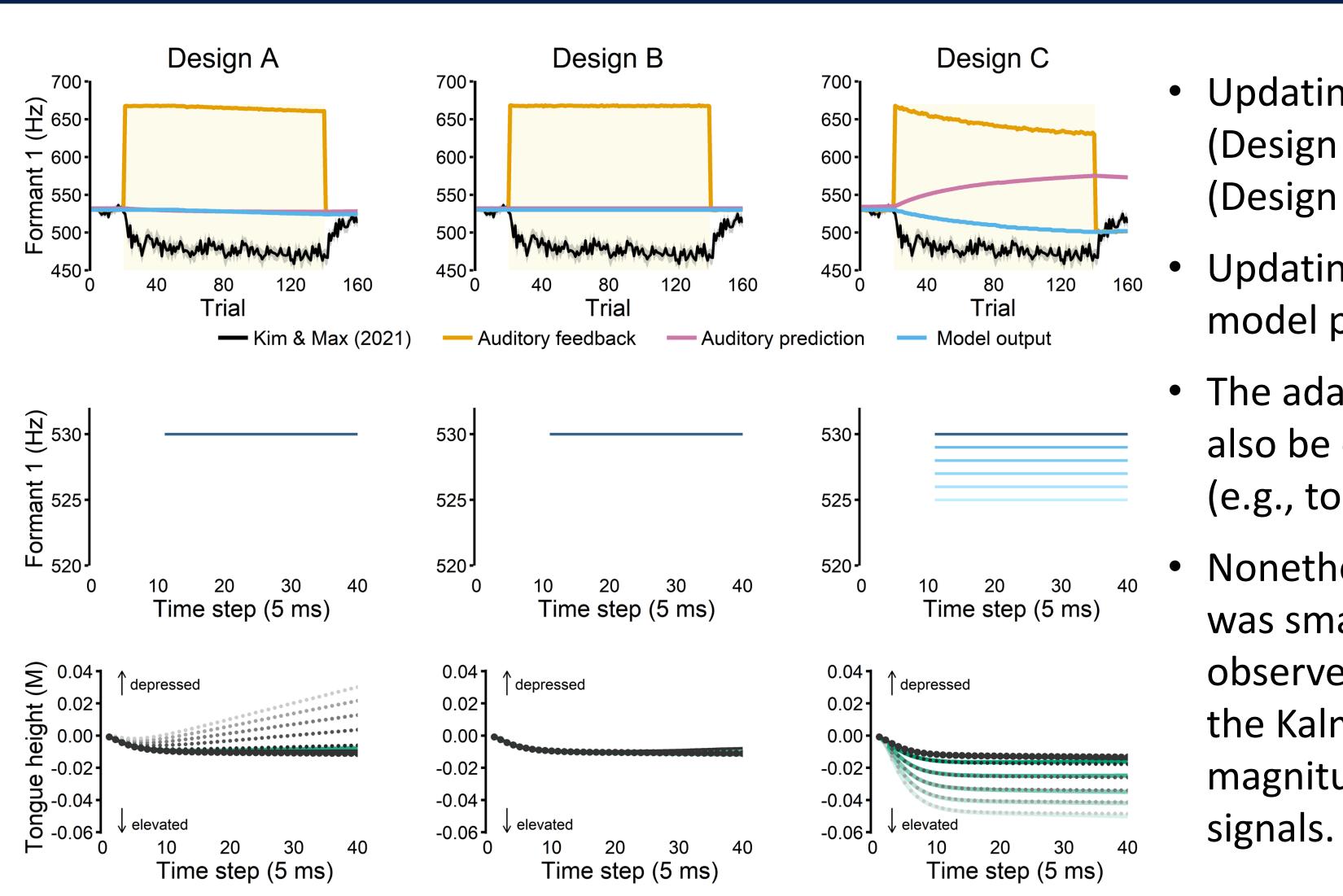
Funded by NIH NIDCD grants (F32DC019538, R01DC007603, R01DC014510).

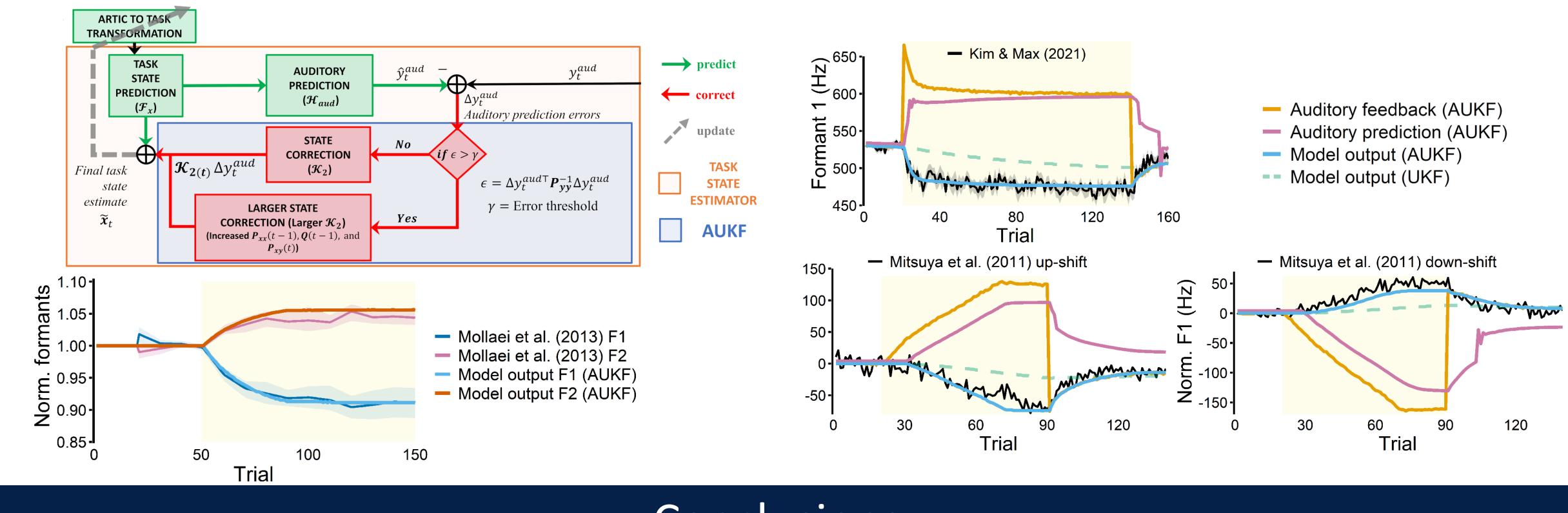
NIH Other Communication Disorders (NIDCD)

Kim, K. S., & Max, L. (2021). Speech auditory-motor adaptation to formant-shifted feedback lacks an explicit component: Reduced adaptation in adults who stutter reflects limitations in implicit sensorimotor learning. The European Journal of Neuroscience, 53(9), 3093–3108. Mitsuya, T., Macdonald, E. N., Purcell, D. W., & Munhall, K. G. (2011). A cross-language study of compensation in response to real-time formant perturbation. The Journal of the *Acoustical Society of America*, *130*(5), 2978–2986. Mollaei, F., Shiller, D. M., & Gracco, V. L. (2013). Sensorimotor adaptation of speech in Parkinson's disease. Movement Disorders: Official Journal of the Movement Disorder Society, 28(12), 1668–1674. Kim, K. S., Gaines, J. L., Parrell, B., Ramanarayanan, V., Nagarajan, S. S., & Houde, J. F. (2023). Mechanisms of sensorimotor adaptation in a hierarchical state feedback control model

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- We found that adaptive behavior was present only when prediction errors updated the articulatory-to-task state transformation.
- In contrast, designs in which prediction errors updated forward sensory prediction models alone did not generate adaptation.
- FACTS demonstrated that prediction errors can drive adaptation through task-level updates.

Design A

Auditory prediction errors updated the forward model that predicted the current articulatory state.

Design B

Auditory prediction errors updated the auditory forward model.

Design C

Used a new

hierarchical architecture with separate state feedback control loops for the articulatory level and the task level.

Auditory prediction errors updated the articulatory-to-task transformation.

Results

Design C implemented with AUKF produces realistic adaptation In order to simulate more realistic sensorimotor adaptation, we implemented a simple adaptive unscented Kalman filter (AUKF) in Design C.

Conclusions



- Updating forward articulatory state (Design A) or sensory prediction models (Design B) did not cause adaptation.
- Updating the task state transformation model produced adaptation (Design C).
- The adaptive changes in Design C could also be observed in the articulatory space (e.g., tongue height).
- Nonetheless, the simulated adaptation was smaller and slower than adaptation observed in experimental data because the Kalman filter assumed a high magnitude of random noise in the sensory



