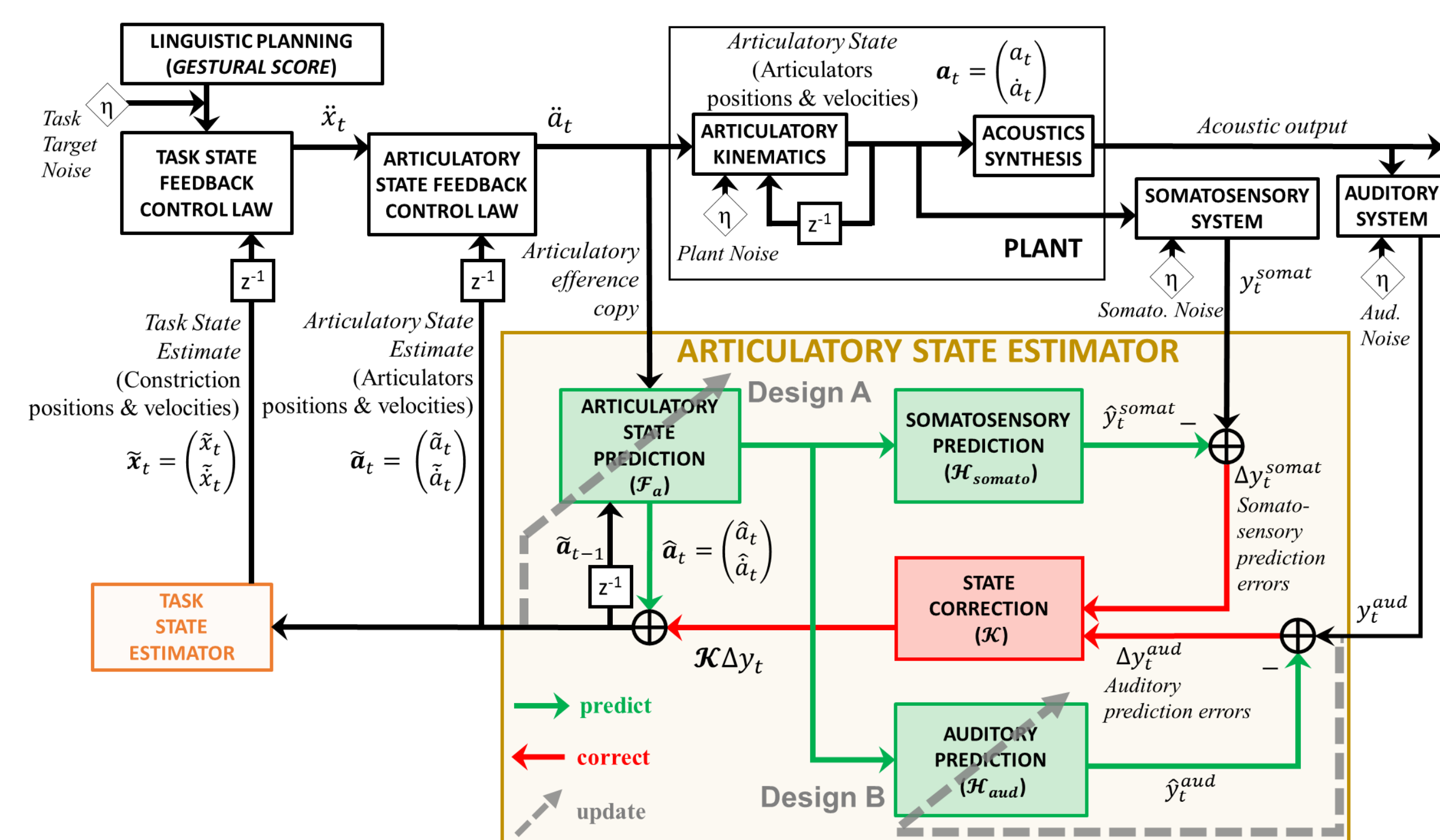


# Sensorimotor adaptation in a hierarchical state feedback control model of speech

## Introduction and Method

- Auditory prediction error-based mechanisms involved in speech auditory-motor adaptation were examined via the feedback aware control of tasks in speech (FACTS) model.
- Consistent with theoretical perspectives in both non-speech and speech motor control, the hierarchical architecture of FACTS relies on both the higher-level task (vocal tract constrictions) as well as lower-level articulatory state representations.

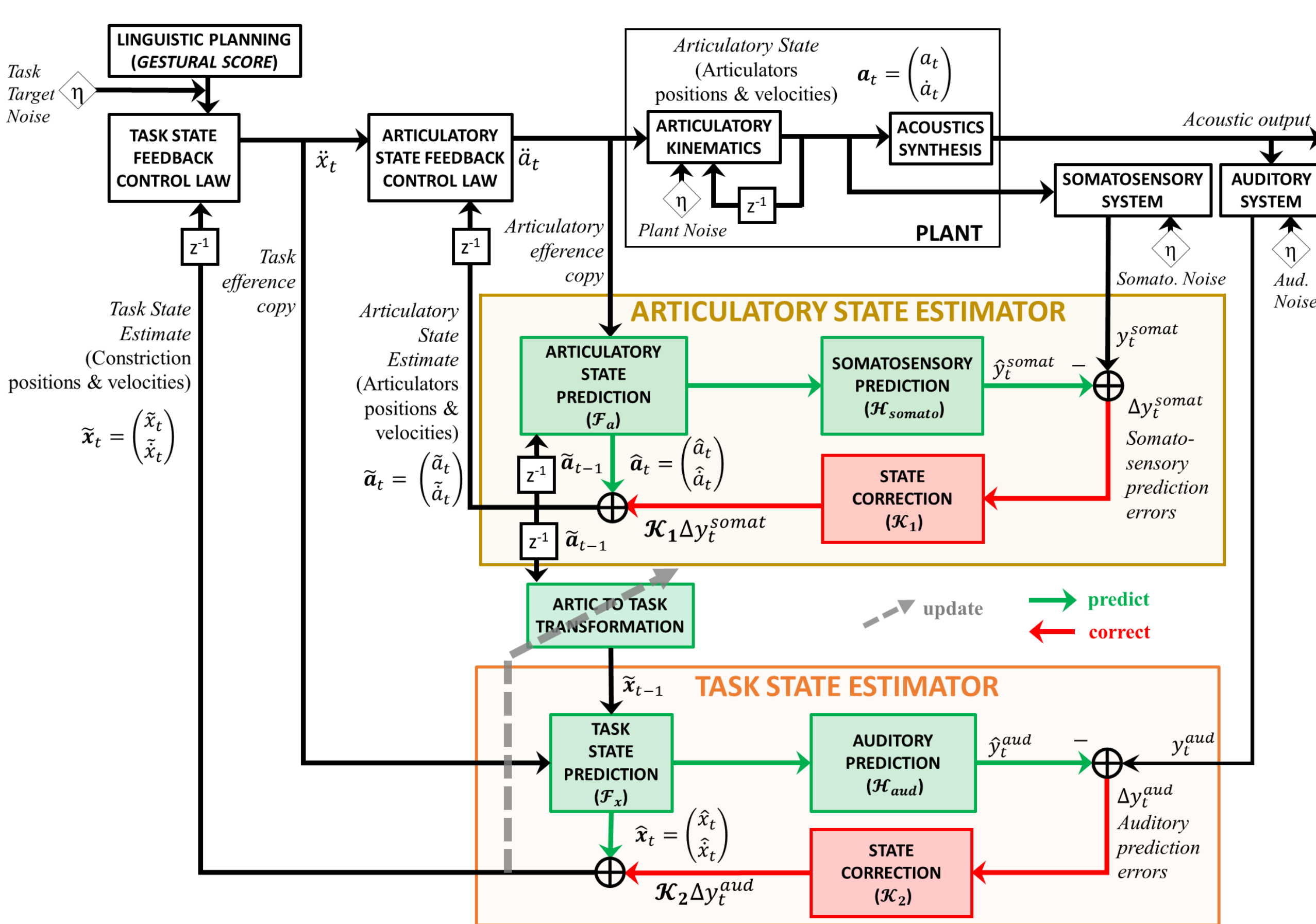


### Design A

Auditory prediction errors updated the forward model that predicted the current articulatory state.

### Design B

Auditory prediction errors updated the auditory forward model.

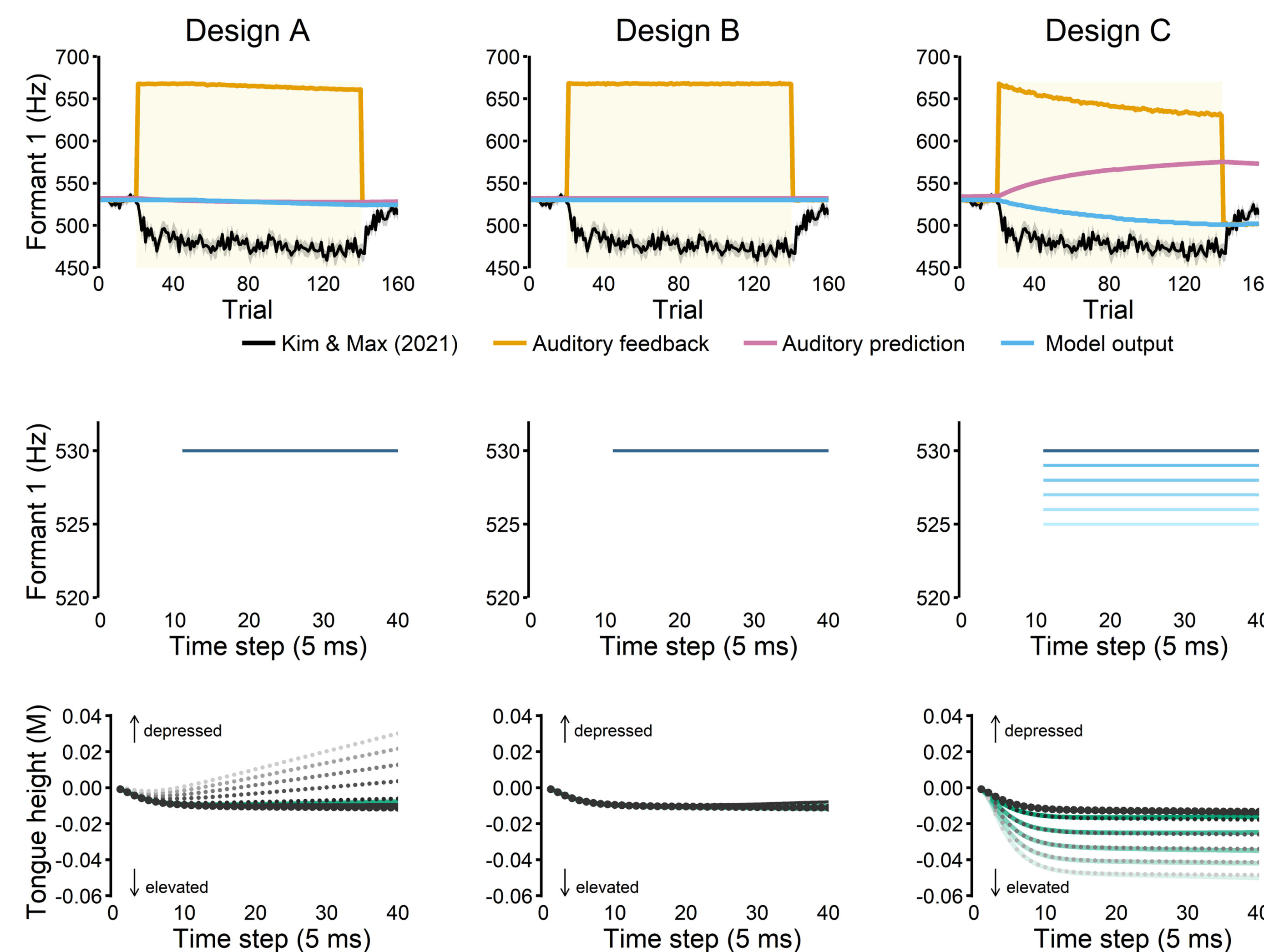


### Design C

Used a new hierarchical architecture with separate state feedback control loops for the articulatory level and the task level.

Auditory prediction errors updated the articulatory-to-task transformation.

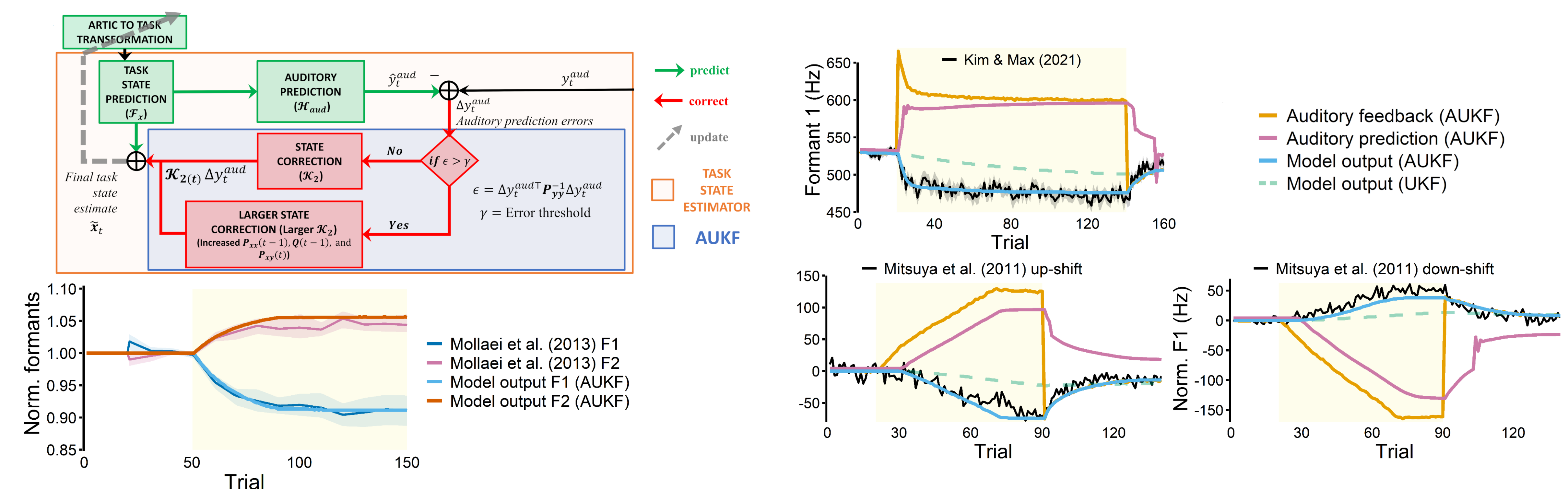
## Results



- Updating forward articulatory state (Design A) or sensory prediction models (Design B) did not cause adaptation.
- Updating the task state transformation model produced adaptation (Design C).
- The adaptive changes in Design C could also be observed in the articulatory space (e.g., tongue height).
- Nonetheless, the simulated adaptation was smaller and slower than adaptation observed in experimental data because the Kalman filter assumed a high magnitude of random noise in the sensory signals.

### Design C implemented with AUKF produces realistic adaptation

In order to simulate more realistic sensorimotor adaptation, we implemented a simple adaptive unscented Kalman filter (AUKF) in Design C.



## Conclusions

- We found that adaptive behavior was present only when prediction errors updated the articulatory-to-task state transformation.
- In contrast, designs in which prediction errors updated forward sensory prediction models alone did not generate adaptation.
- FACTS demonstrated that prediction errors can drive adaptation through task-level updates.

Check out our paper!

